

APPENDIX B

Agenda Item 7d Autonomous Vehicle Demonstration Project

Board of Directors Meeting

Wednesday December 16, 2020



Partnership Overview



Operations

First Transit

Staffing

MAX/TONY AV stack solution and Engineering

Perrone Robotics









PERRONE ROBOTICS

First 😘 Transit





GreenPower Motor Company

Vision: Advancing the adoption of electric vehicles by making battery-electric buses and trucks affordable, durable, and easy for customers to deploy

- Founded in 2010
- Purpose-built commercial electric vehicles for a broad range of service types
- Vehicles capable of autonomous operation and wireless charging
- Manufacturing located in Porterville, CA
- Sales Admin office located in Rancho Cucamonga, CA











Perrone Robotics, Inc.

Vision: One Software Platform, Any Autonomous Application

35,000 automated miles traveled Tony 17 years of autonomy experience 150 man-years of team AV experience More than 30 Two US patents with vehicles automated others pending







First Transit

Vision: We provide easy and convenient mobility, improving quality of life by connecting people and communities







10 AV deployments

20,000 employees

65 years in business







US, Canada, and Puerto Rico



300+ contracts



318m passengers per year







Project Plan

Deploy an Automated Vehicle in public transit operation

- Level 4 automated vehicle within existing service
- Within micro-mobility 'MyRide' service
 - On-demand, rideshare service
 - Service area around Pittsburg or Antioch BART stations
 - Monday-Friday, 5a-9p service
- AV Star to supplement existing fleet



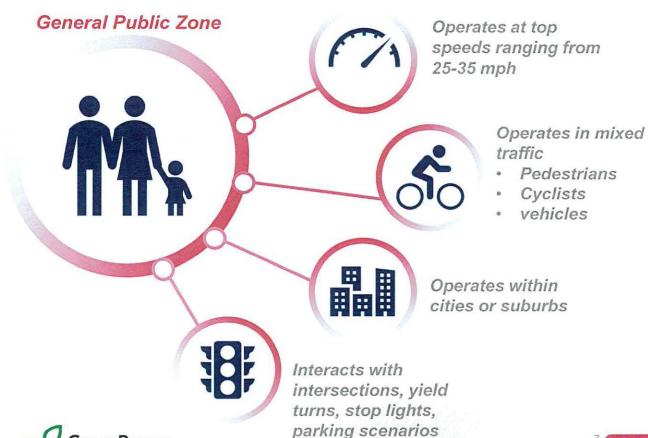




Operational Design Domain

Level 4 Automation (operator present onboard)











Typical PRI sensor setup



FMVSS capable vehicle, Altoona-Tested and verified

Cameras used for lane-keeping, traffic signal detection and analysis

Multiple 3D lidars view front and sides and overlap for safety/ reliability

RADAR provides longer-range inputs and better fusion results when following traffic







Hardware Functionality

Sensor Type	Location	Purpose
GPS/INS/IMU	Top of vehicle	Aid in localization of shuttle. GPS corrections provide < 10cm accuracy, typically 2-4 cm.
Lidar	2 front corners, 1 center rear, others as required by ODD	Detailed views of road and surroundings of shuttle during operations. Effective to 100 meters but can see reflective objects farther out.
Long-range Radar	Front	Identify objects at greater distance to enable higher speed operations. Also provide object speed estimation.
Medium-range Radar	Front and read, left and right sides	Enable view of vehicles approaching intersections from the side to allow merging at intersections. Also useful for merging.
Cameras	2, front	Traffic light location and state detection. Also lane edge detection used for navigation when GPS quality is poor.
Ultrasonics	Front/Rear as needed	Used for close-in maneuvering where obstacles are within about 3 meters or less.







Partnership Roles









First Transit

- Onboard operator staffing and supervision
 - Training
- Risk assessment and site analysis
- Community engagement
 - Public outreach
 - First responder training
- Data collection and reporting
- Vehicle maintenance support









GreenPower Motors

EV Star

Purpose-built electric medium-duty vehicle

Up to 150-mile range

Vehicle Capacity

19 forward-facing passenger seats

12 passenger seats + 2 wheelchairs

118 kWh Battery

 Capacity Standard J1772 Plug-in Charger

Optional DC Fast Charging up to 50kW



Perrone Robotics

Autonomy Kit

Hardware

Software

Engineering

Route setup and tuning

Training assistance

Technical Support





Tri Delta – Eastern Contra Costa Transit Authority







Deployment

- January 2021 (at earliest)
 - Route setup and tuning
- Operation
 - Within existing micro-mobility 'MyRide' service
 - · On-demand, rideshare service
 - Service area around Pittsburg and Antioch BART stations
 - Monday-Friday, 5a-9p service







